

Operating and Assembly Instructions Incremental hollow shaft encoder FGH 8

Read the operating and assembly instructions prior to assembly, starting installation and handling! Keep for future reference!



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Court of registration: Giessen
Commercial register number: HRB 126

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1 General

1.1 Information about the Operating and Assembly Instructions

These Operating and Assembly Instructions provide important instructions for working with the device. They must be carefully read prior to starting all tasks, and the instructions contained herein must be followed.

In addition, applicable local regulations for the prevention of industrial accidents and general safety regulations must be complied with.

1.2 Scope of delivery

Incremental hollow shaft encoder FGH 8, Operating and Assembly Instructions.

1.3 Explanation of symbols

Warnings are indicated by symbols in these operating and assembly instructions. The warnings are introduced by signal words that express the scope of the hazard.

The warnings must be strictly heeded; you must act prudently to prevent accidents, personal injury, and property damage.



WARNING!

Indicates a possibly dangerous situation that can result in death or serious injury if it is not avoided.



CAUTION!

Indicates a possibly dangerous situation that can result in minor injury if it is not avoided.



CAUTION!

Indicates a possibly dangerous situation that can result in material damage if it is not avoided.



NOTES!

Indicates useful tips and recommendations as well as information for efficient and trouble-free operation.



NOTES!

Do not use a hammer or similar tool when installing the device due to the risk of damage occurring to the bearings or coupling!



DANGER!

Life-threatening danger due to electric shock! Indicates a life-threatening situation due to electric shock. If the

Indicates a life-threatening situation due to electric shock. If the safety instructions are not complied with there is danger of serious injury or death. The work that must be executed should only be performed by a qualified electrician.



1.4 Disclaimer

All information and instructions in these Operating and Assembly Instructions have been provided under due consideration of applicable guidelines, as well as our many years of experience.

The manufacturer assumes no liability for damages due to:

- Failure to follow the instructions in the operating and assembly instructions
- Non-intended use
- Deployment of untrained personnel
- Opening of the device or conversions of the device

In all other aspects the obligations agreed in the delivery contract as well as the delivery conditions of the manufacturer apply.

1.5 Copyright

NOTES!



Content information, text, drawings, graphics, and other representations are protected by copyright and are subject to commercial property rights.

It is strictly forbidden to make copies of any kind or by any means for any purpose other than in conjunction with using the device without the prior written agreement of the manufacturer. Any copyright infringements will be prosecuted.

1.6 Guarantee terms

The guarantee terms are provided in the manufacturer's terms and conditions.

1.7 Customer service

For technical information personnel is available that can be contacted by telephone, fax or email. See manufacturer's address on page 2.

2 Safety



DANGER!

This section provides an overview of all the important safety aspects that ensure protection of personnel, as well as safe and trouble-free device operation.

If these safety instructions are not complied with significant hazard can occur.

2.1 Responsibility of the owner

The device is used in commercial applications. Consequently the owner of the device is subject to the legal occupational safety obligations and subject to the safety, accident prevention and environmental protection regulations that are applicable for the device's area of implementation.

2.2 Intended use

The device has been designed and constructed exclusively for the intended use described here.

Series FGH 8 Incremental hollow shaft encoder are used for measurement of rotations, for instance of electrical and mechanical drives and shafts.

Claims of any type due to damage arising from non-intended use are excluded; the owner bears sole responsibility for non-intended use.

2.3 Improper use

- Do not use the device in potentially explosive areas.
- The device must not be subjected to mechanical loads in addition to its own weight and unavoidable vibration and shock loads that arise during normal operations.

Examples for non-permitted mechanical loads (incomplete list):

- Fastening transport or lifting tackle to the device, for example a crane hook to lift a motor.
- Fastening packaging components to the device, for example ratchet straps, tarpaulins
- Using the device as a step, for example by people to climb onto a motor.

2.4 Personal protective equipment

For tasks such as assembly, disassembly or commissioning the use of personal protective equipment such as safety footwear and protective work clothing is required.

The regulations specified by the owner and that are locally specified apply.

2.5 Personnel

Installation and commissioning as well as disassembly routines must be carried out by skilled technical staff only.



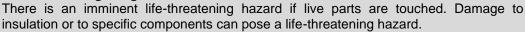
2.6 Special dangers

Residual risks that have been determined based on a risk assessment are cited below.

2.6.1 Electrical current

DANGER!

Life-threatening danger due to electrical shock!





Therefore:

Immediately switch off the device and have it repaired if there is damage to the insulation of the power supply.

De-energize the electrical equipment and ensure that all components are connected for all tasks on the electrical equipment.

Keep moisture away from live parts. Moisture can cause short circuits.

2.6.2 Rotating shafts / Hot surfaces

WARNING!

Danger of injury due to rotating shafts and hot surfaces!

Touching rotating shafts can cause serious injuries.



Therefore

Do not reach into moving parts/shafts or handle moving parts/shafts during operation. Close to protect from injury all access openings in flanges with the corresponding plug screw, and provided you exposed rotating components with protective covers.

Do not open covers during operation. Prior to opening the covers ensure that all parts have come to a standstill.

The encoder can become hot during prolonged use.

In case of contact, risk of burns is existing.

2.6.3 Safeguarding against restart

DANGER!



Life-threatening danger if restarted without authorization!

When correcting faults there is danger of the power supply being switched on without authorization.

This poses a life-threatening hazard for persons in the danger zone.

Therefore:

Prior to starting work, switch off the system and safeguard it from being switched on again.



3 Technical Data

3.1 Type plate

The figure below shows an example of a nameplate:



Encoder with 2 terminal boxes

The type plate is located on the outside of the housing and contains the following information:

- Manufacturer, Address
- Type, Year of construction
- CE marking
- Serial number (S/N)
- Commission number (C/N)
- Pulse rate
- Protection class
- Power supply

3.2 Electrical and mechanical data

Pulse rates	Value
Preferred Pulse Rates	1024, 2800, 4096
Special pulse rates	600, 720, 750, 1000, 1200, 2048, 2560

Connection data		
Supply voltage	12 V to 30 V DC (option 5 V DC) Ripple max. 10 %	
No load-current	approx. 100 mA at 30 V (without Option)	
Outputs 1)	Push-pull final stages, resistant to short-circuit	
Pulse height (HTL)	approx. as supply voltage, special output:	
Output current	50 mA per output	
Internal resistance	$50~\Omega$ per output	
Slew rate	50 V / μs	

1) Special output voltage 5V

(specify on order)

Supply voltage: 12 V to 20 V DC or 20 V to 30 V DC Outptus: push-pull output stages with inverted signals.

Pulse height: 5 V to RS 422.



Pulse duty factor	1:1 ± 5 %		
Square wave displacement 0°, 90°	to 50 kHz < 3 % to 150 kHz < 5 %		
Max. frequency	0 to 100 kHz (150 kHz on request)		
Encoder temperature ranges	ncoder temperature ranges		
Standard	0°C to + 70°C		
Special temperature ranges	-25°C to + 85°C		
Special output voltage 5V (TTL)			
Pulse height	5V, RS422-compatible (TIA/EIA-Standard)		
Supply voltage	12 to 30 V DC		
Ambient temperature			
The max. permissible ambient temperature depends on the speed and degree of protection of the device.			

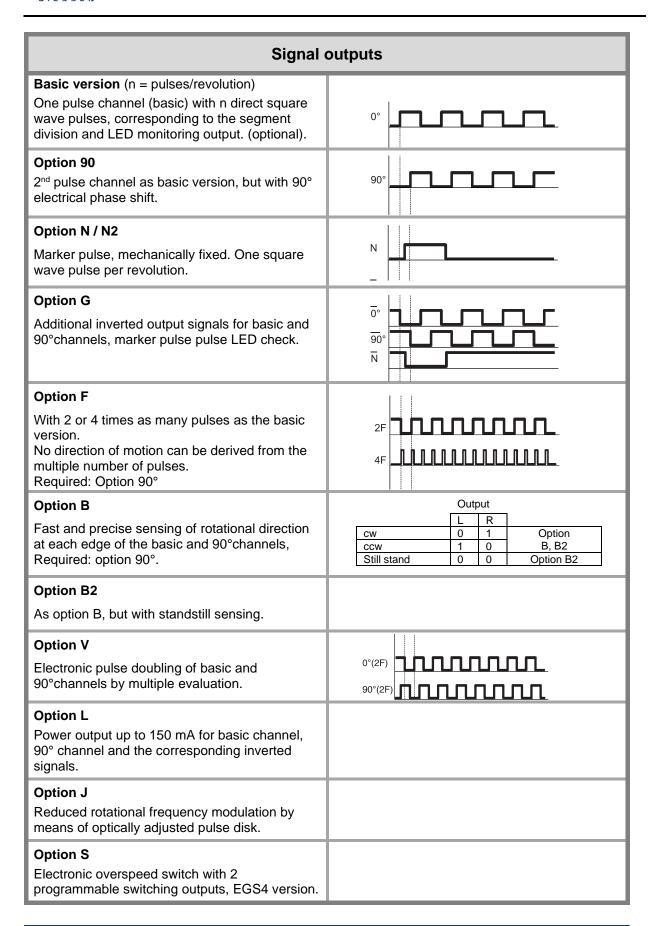
Protection class acc. to DIN EN 60529	Sealing	Mechanical speed	Description	Breakaway torque
IP 54	Special seal	≤ 3000 rpm	Protection against dust and water spray	aprrox. 20 to 60 Ncm
IP 56** both sides	Radial shaft seal	≤ 1200 rpm	Protection against dust and water spray	approx. 60 Ncm
IP 66	Radial shaft seal		Protection against dust and water spray	approx. 70 – 100 Ncm

^{**}Higher speed on request. Seals and attachments increase the breakaway torque.

Only DE side with gasket of radial shaft / NDE side with cover / Sealing or overall protection class IP 56 feasible.

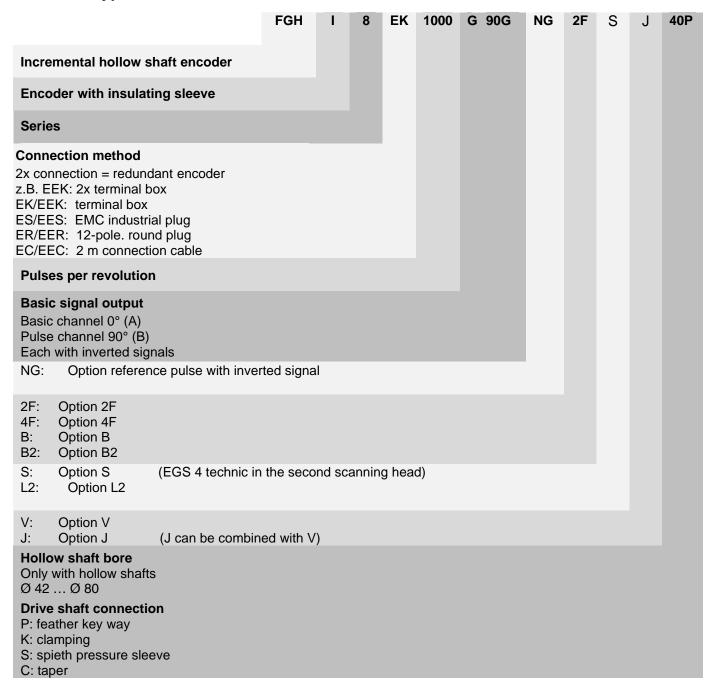
DE = drive end side, NDE = Non drive end side

Weight	Type EK	approx. 13 kg
vvoigin	Type EEK	approx. 14,2 kg





3.3 Type code





4 Transport, packaging and storage

4.1 Safety instructions for transport

CAUTION!

Material damage caused by improper transport!

Observe the symbols and information on the packaging:

- Do not throw risk of breakage
- Keep dry
- Do not expose to heat above 40 °C or direct sunlight.

4.2 Incoming goods inspection

Check delivery immediately upon receipt for completeness and possible transport damage.

Inform the forwarder directly on receipt of the goods about existing transport damages (prepare pictures for evidence).

4.3 Packaging / disposal

The packaging is not taken back and must be disposed of in accordance with the respective statutory regulations and local guidelines.

4.4 Storage of packages (devices)



Keep dry

Keep packages dry and free from dust; protect from moisture.



Protect against heat

Protect packages from heat above 40 °C and direct sunlight.

If you intend to store the device for a longer period of time (> 6 months) we recommend you use protective packaging (with desiccant).



NOTES!

Turn the shaft of the device every 6 month 10 times to prevent a possible hardening of the grease-filling of the ball bearings, which may lead to the destruction of the device.



5 Installation and commissioning

5.1 Safety instructions

Personnel

Installation and commissioning must be carried out by skilled technical staff only.

 \bigcap_{1}°

NOTES!

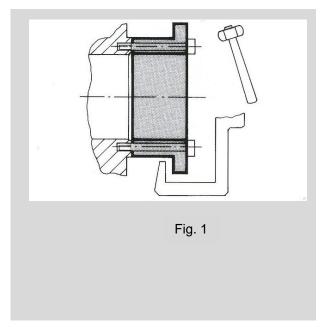
Observe the safety instructions contained in **Chapter 2** when installing or working on the device!

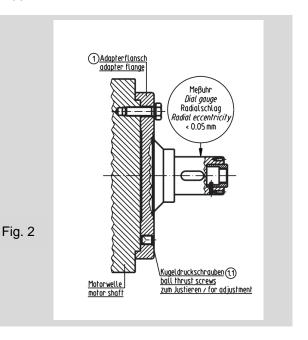
5.2 Mounting of the encoder (mechanical)

Mounting and disassembly by means of a hammer or similar tools in not permitted (warranty void).

5.2.1 Mounting Instruction for hollow shaft encoder

- 1. Adapter flange has to be mounted and to be aligned by dial gauge, if necessary optimize by ball thrust adjusting screws.
- 2. Ball thrust screws to be fastened with Loctite, remove non-fastened screws of fasten with Loctite! Max. torque for M12 approx. MD 25 Nm / M16 approx. MD 35 Nm.





The hollow shafts has tapped holes on both sides at the front. For removal use screws to attach the mounting sleeve, and then use a puller to draw off the unit. A suitable mounting sleeve is recommended for each plant area (specify on ordering). Remove hollow shaft encoders using mounting sleeve only:

Mounting / removal sleeves for standard bores		
FGH 8	Drg. no. E-52 443a	
FGH 8 / B 14	Drg. no. E-52 760	
	Only mounting sleeve	



NOTES!

The radial deviation of the shaft (\(\simple \rightarrow \text{Fig. 2} \)) should not exceed 0,05 mm.

- 3. Use feather keys in accordance with DIN 6885.
- 4. Mount the torque bracket / torque arm on the housing.



NOTES!

Comply with the information provided in the supplemental data sheet entitled "Mounting Accuracy of hollow shaft encoders".

- 5. Check the mounting position relative to the terminal box, adjust if necessary.
- 6. Push the device onto the shaft that has been lightly greased.



CAUTION!

Danger of damage to shaft and device if improperly handled.

Ensure that there are no hard impacts on hollow shaft and housing. Use the mounting sleeve.

- 7. Fasten axial tensioning elements. (Screw, axial clamping shoes or flange).
- 8. Tighten the fastening screws on the link head of the torque bracket. Fix the nuts in place with locknuts.
- Check the attached torque brackets:
 The link rod must be easy to turn within the link head, and the link heads should not tilt. If this instruction is not followed there is a danger of bearing damage.
- 10. Connect the cabling in the terminal box (Appendix, connecting diagrams).



5.3 Connecting the encoder

5.3.1 Connections

Cable glands are closed with a stopper to protect the devices on transport and storage.

Cable connections:

Have to be executed according to the encoder type.

Connection diagrams have to be considered!

Use of connection cables with diameter of min. 17.5 mm – max. 20 mm is essential to ensure the protection class. Cable outlet should show preferably downwards.

Option:

R: 12 - pole round plug.

S: Industrial plug

C: Connection cable

Wiring arrangement and shielding

(EMI measurement)

The cable shielding must be placed on both sides.

The shield of the signal cable has to be connected directly to the housing of the encoder by the cable gland.

You must observe applicable EMC guidelines when routing cables.





Special note!

The connection must be carried out by skilled technical staff only.

Closing the terminal box cover:

Check the seal of the terminal box cover, clean it if soiled. Then duly close the cover.



Note!

Cable must not be pinched.

Attention with open terminal boxes:

Moisture should not get into the terminal box when connecting the cable.

5.3.2 Technical note

Ambient temperature

The permissible ambient temperature depends on the speed and degree of protection (shaft seal) of the device and the frequency, the signal cable length and mounting situation. See chapter 3.2

Degree of protection

To fulfill degree of protection requirements the diameter of the connection cable must correspond to that of the cable gland. Please refer to Chapter 5.3.1.

6 Dismantling

6.1 Safety instructions



Personnel:

Dismantling must be carried out by skilled technical staff only.

Observe the safety instructions contained in Chapter 2 when dismantling the device!

6.2 Dismantling the encoder

To dismantling the encoder follow the instructions give in chapter 5.2 in the reverse order.



7 Faults

7.1 Faults table

Faults	Possible cause	Remedy		
	Soiled terminal box gasket or seal surfaces	Clean terminal box gasket and seal surfaces		
	Damaged terminal box gasket	Replace terminal box gasket		
Moisture in the terminal box	Cable gland/blanking plug not tightened	Tighten cable gland/blanking plug		
	Unsuitable cable for cable gland	Use suitable cable and cable glands		
No output signals	Supply voltage not connected	Connect supply voltage		
	Connection cable reversed	Wire correctly		
	Unsuitable cable	Use data cable with conductors arranged as twisted pairs and common shield		
Output signals subject to interference	Cable shield not connected	Connect cable shield at both ends		
	Cable routing not EMC compliant	Observe applicable EMC guidelines when routing cables		
	Signal end stage overloaded	Check pin assignment; observe connection diagram		
Signal interruptions		Do not assign unused outputs		
	Outputs short-circuited	Do not connect outputs with supply voltage or GND		
Contact Hubner-Service (Contact Hubner-Service (page 2) if none of the remedies listed above provides a solution)!			



Inspections

8.1 Safety instructions



Personnel

Skilled technical staff only are permitted to inspect the device and its installation. Observe the safety instructions contained in Chapter 2 when inspecting or working on the

8.2 Maintenance information

The device is maintenance-free. However, to guarantee optimum fault-free operations we recommend that you carry out the following inspections.

8.3 Inspection schedule

Interval	Inspections	Tasks
All 12 month	Check coupling	Qualified person
All 12 month	Check the fastening screws for firm seat	Qualified person
	Check the cable connections	Qualified person
After approx. 16000 to 20000 operating hours and high long-term loading	Check deep-groove ball bearing for ease of movement and noise.	Qualified person
	Worn ball bearings have to be replaced only by the Manufacturer	Hubner – Giessen Service



9 Disposal

9.1 Disposal procedure

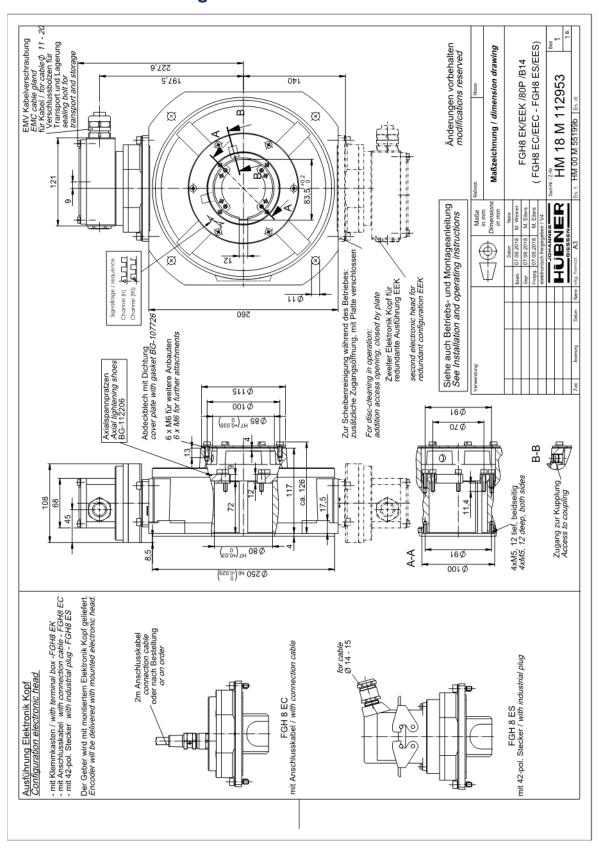
The manufacturer is not obliged to take back the device.

The device is classed as electronic equipment and subject to the WEEE Directive; observe local, country-specific laws when disposing of the device.

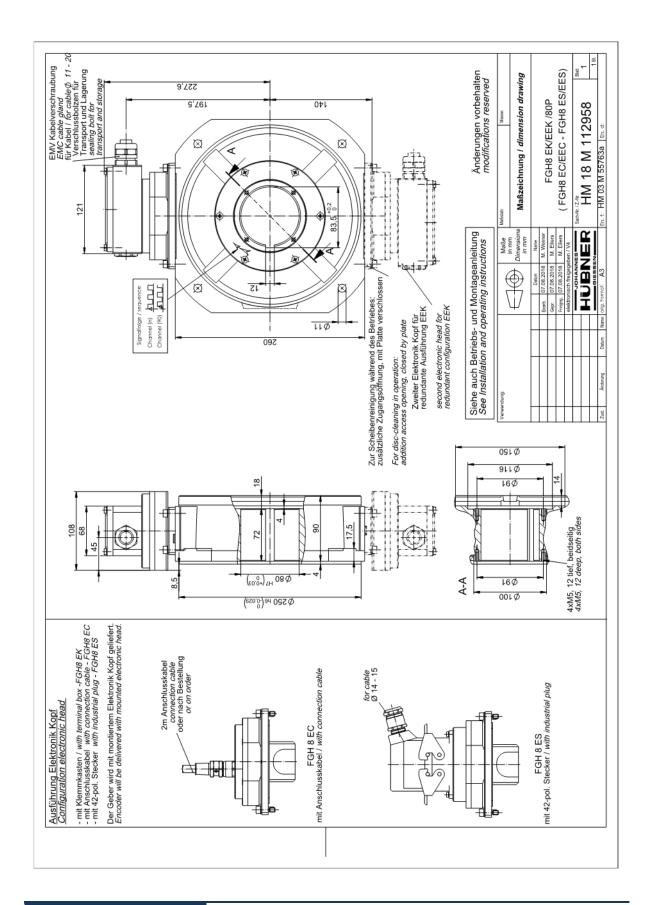
For information on environmentally sound disposal please contact your local authority or a specialist disposal company.



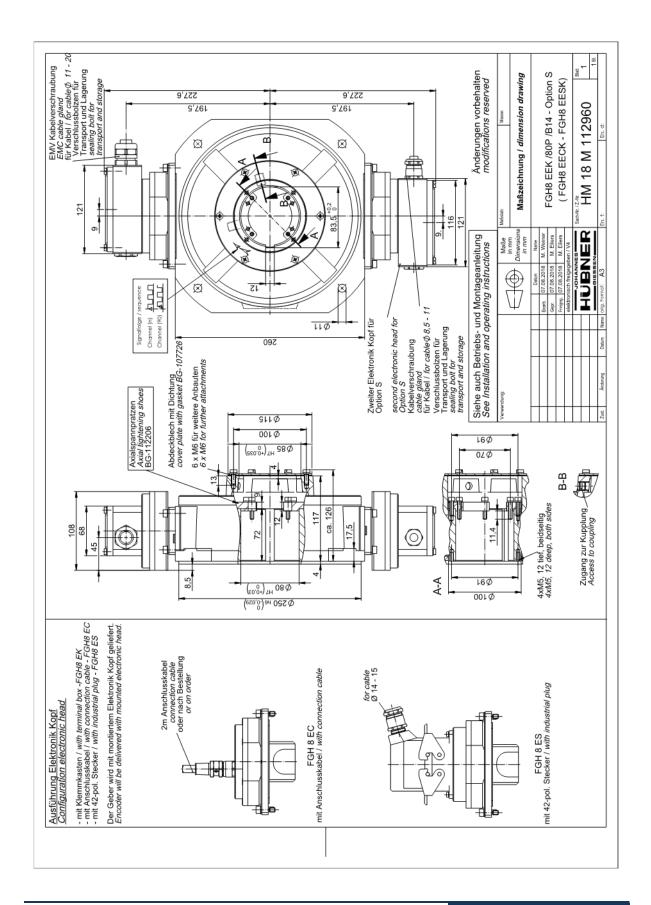
10 Dimension drawings



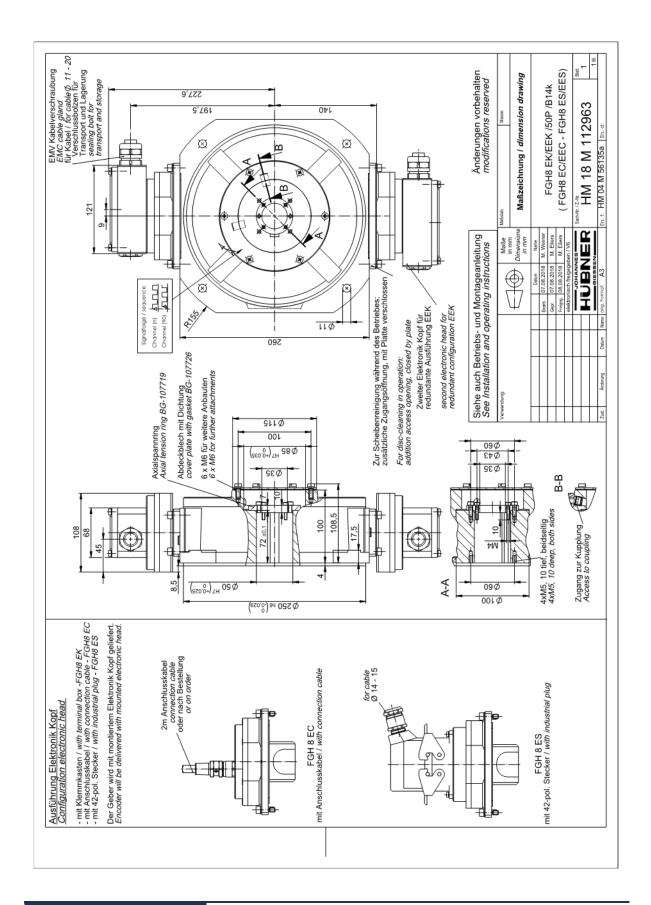




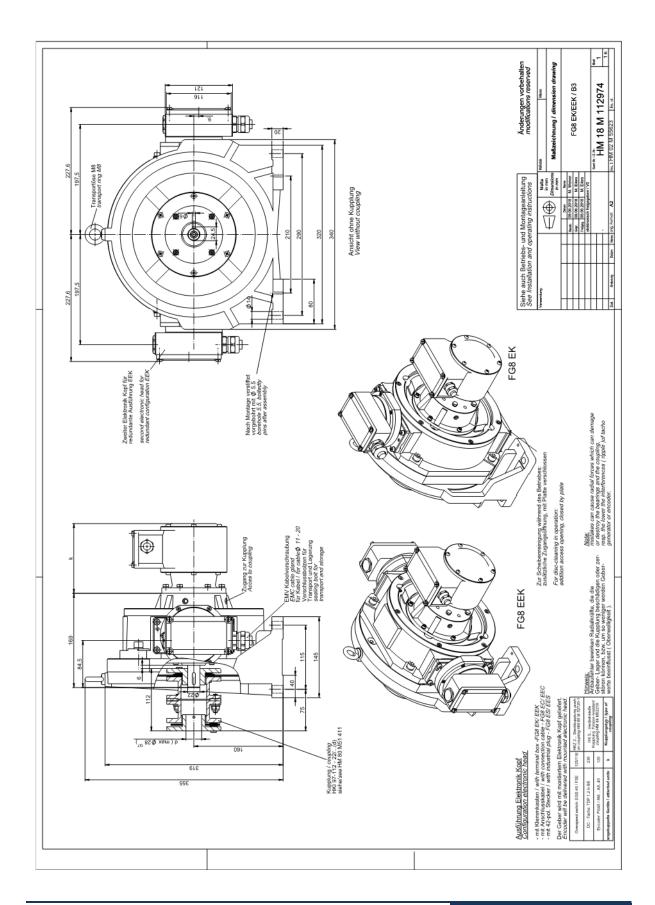




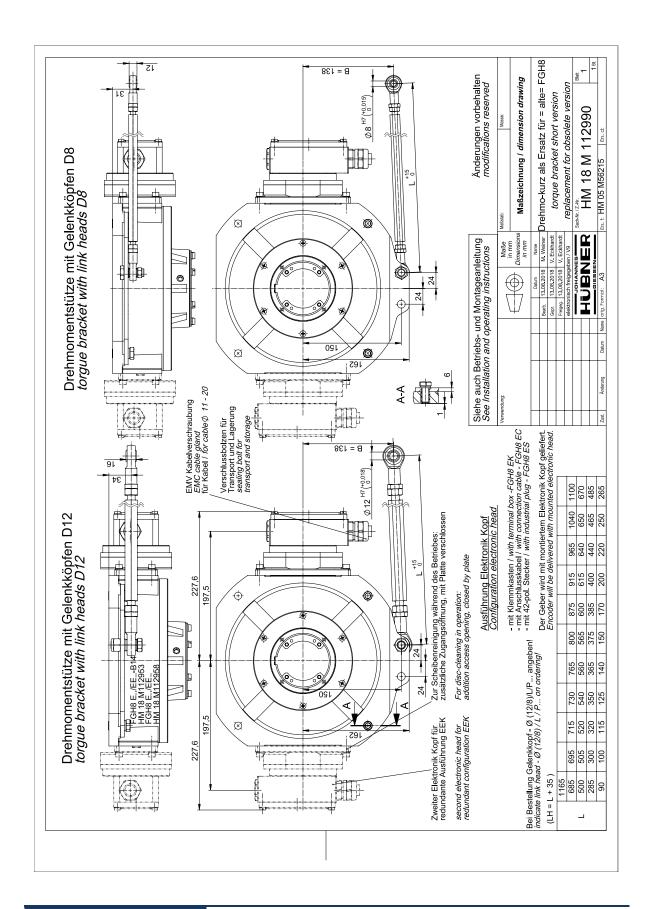




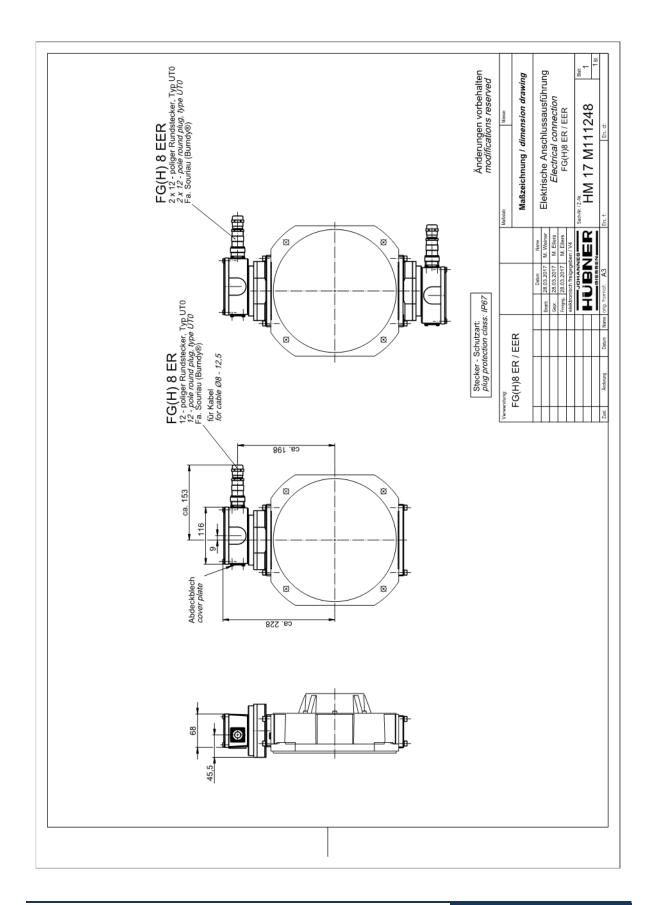






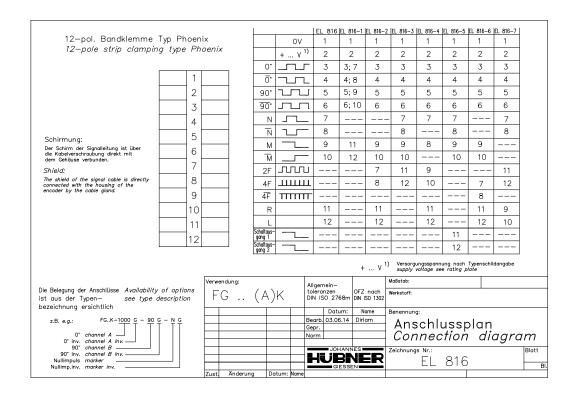




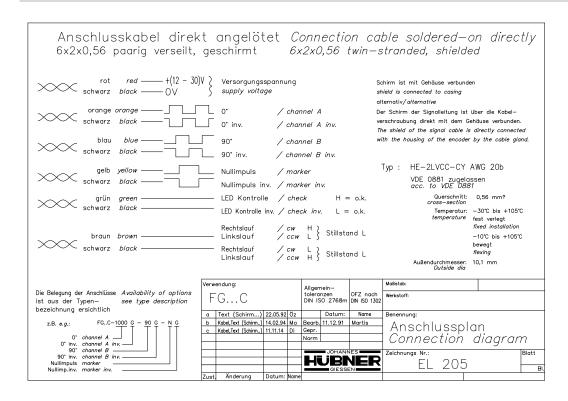




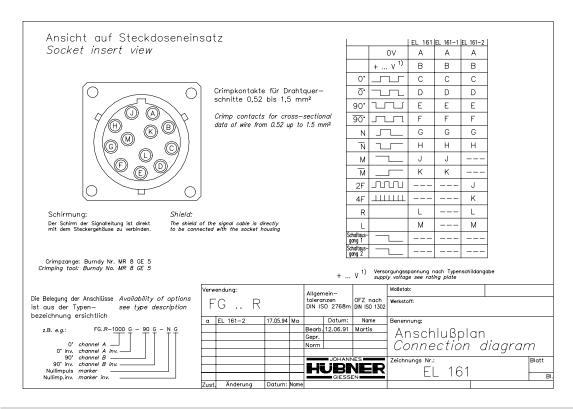
11 Connections



FGH 8 standard terminal box



FGH 8 standard connection cable

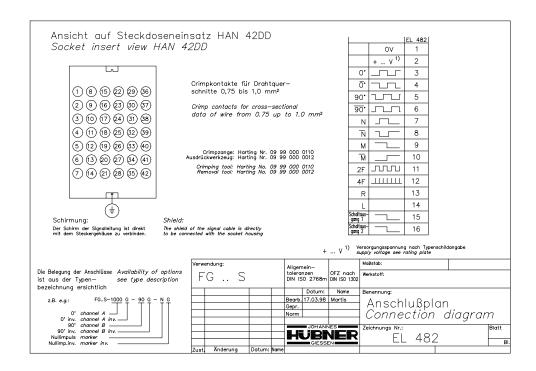


FGH 8 standard 12 – pole round plug

Ansicht auf Steckdosenei	nsatz	EL 064 EL 064-1
Socket insert view		0V C5 C5
		+ v ¹⁾ A5 A5
		0°
A B C	Crimpkontakte für Drahtquer-	Ō° ☐ ☐ A2 A2
	schnitte 0,75 bis 1,0 mm²	90° 7_7_1 A3 A3
	Crimp contacts for cross—sectional	90°
	data of wire from 0.75 up to 1.0 mm²	N _ B3 B3
(3) (3) (3)		N 7_ B4 B4
		M B5 B5
4 4 4	Crimpzange: Harting Nr. 09 99 000 0110 Ausdrückwerkzeug: Harting Nr. 09 99 000 0012	M C3 C3
	Crimping tool: Harting No. 09 99 000 0110 Removal tool: Harting No. 09 99 000 0012	2F C4
5 5 5	,	4F 111111 B2
		R C1 C1
		L C2 C2
Schirmung: Shield:		Schaltaus- — B1
Der Schirm der Signalleitung muss über The shie.	ld of the signal cable has to be Id directly to the housing of the	Schaltaus B2
	by the cable gland.	
	+	 Versorgungsspannung nach Typenschildangabe supply voltage see rating plate
	Verwendung: Allgemein-	Maßstab:
Die Belegung der Anschlüsse Availability of options ist aus der Typen— see type description bezeichnung ersichtlich	FG S toleranzen DIN ISO 2768m DIN	nach ISO 1302 Werkstoff:
	a att / stigit	Name Benennung:
z.B. e.g.: FGS-1000 G - 90 G - N G	b EMV—Harting 29.04.11 Di Bearb. 24.09.92 Mar Gepr.	Anschlussplan Connection diagram
0° channel A — 0° inv. channel A inv. —	Norm	— Connection diagram
90° channel B ———————————————————————————————————	JOHANNES	Zeichnungs Nr.: Blatt
Nullimpuls marker Nullimp.inv. marker inv.	HUBNI	ER 064
	Zust. Änderung Datum: Name	

FGH 8 standard 15 – pole industrial plug





FGH 8 standard 42 pole industrial plug